On the solvability of inhomogeneous boundary-value problems in Sobolev spaces

## Olena Atlasiuk

joint work with Professor Volodymyr Mikhailets
Institute of Mathematics of the National Academy of Sciences of Ukraine
Institute of Mathematics of the Czech Academy of Sciences

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## The aim of the talk is

to present the results about the character of solvability of systems of linear differential equations of arbitrary order on a finite interval with the most general inhomogeneous boundary conditions. Boundary conditions can be both overdetermined and underdetermined. These boundary-value problems have essential features and require new research methods.

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(1) Generic boundary conditions
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## Generic boundary conditions

## Statement of the problem

Let a finite interval $(a, b) \subset \mathbb{R}$ and parameters $\{m, n, r, l\} \subset \mathbb{N}, 1 \leq p \leq \infty$, be given.
Linear boundary-value problem

$$
\begin{equation*}
(L y)(t):=y^{(r)}(t)+\sum_{j=1}^{r} A_{r-j}(t) y^{(r-j)}(t)=f(t), \quad t \in(a, b) \tag{1}
\end{equation*}
$$

$$
\begin{equation*}
B y=c . \tag{2}
\end{equation*}
$$

Here, $A_{r-j}(\cdot) \in\left(W_{p}^{n}\right)^{m \times m}, f(\cdot) \in\left(W_{p}^{n}\right)^{m}, c \in \mathbb{C}^{l}$, linear continuous operator

$$
\begin{equation*}
B:\left(W_{p}^{n+r}\right)^{m} \rightarrow \mathbb{C}^{l} \tag{3}
\end{equation*}
$$

are arbitrarily chosen; $y(\cdot) \in\left(W_{p}^{n+r}\right)^{m}$ is unknown.

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are arbitrarily chosen; $y(\cdot) \in\left(W_{p}^{n+r}\right)^{m}$ is unknown.
The solutions of equation (1) fill the space $\left(W_{p}^{n+r}\right)^{m}$ if its right-hand side $f(\cdot)$ runs through the space $\left(W_{p}^{n}\right)^{m}$. Hence, the condition (2) with operator (3) is generic condition for this equation.

## Statement of the problem

It includes all known types of classical boundary conditions and numerous nonclassical conditions containing the derivatives (in general fractional) of an order $\geq r$.

Thus, boundary conditions can contain derivatives whose order is greater than the order of the equation.

If $l<r$, then the boundary conditions are underdetermined.
If $l>r$, then the boundary conditions are overdetermined.

## Example 1 (one-point problem)

Linear one-point boundary-value problem

$$
\begin{gathered}
(L y)(t):=y^{(r)}(t)+\sum_{j=1}^{r} A_{r-j}(t) y^{(r-j)}(t)=f(t), \quad t \in(a, b) \\
B y=\sum_{k=0}^{n+r-1} \alpha_{k} y^{(k)}(a)=c
\end{gathered}
$$

Here, $A_{r-j}(\cdot) \in\left(W_{p}^{n}\right)^{m \times m}, f(\cdot) \in\left(W_{p}^{n}\right)^{m}, c \in \mathbb{C}^{l}, \alpha_{k} \in \mathbb{C}^{l \times m}$ are arbitrarily chosen; $y(\cdot) \in\left(W_{p}^{n+r}\right)^{m}$ is unknown.
Here, $m$ is the number of differential equations of order $r$, $l$ is the number of scalar boundary conditions.

## General case

In case $1 \leq p<\infty$, the linear continuous operator $B:\left(W_{p}^{n+r}\right)^{m} \rightarrow \mathbb{C}^{l}$ admits the unique analytic representation

$$
\begin{equation*}
B y=\sum_{k=0}^{n+r-1} \alpha_{k} y^{(k)}(a)+\int_{a}^{b} \Phi(t) y^{(n+r)}(t) \mathrm{d} t, \quad y(\cdot) \in\left(W_{p}^{n+r}\right)^{m} \tag{4}
\end{equation*}
$$

Here, the matrices $\alpha_{k} \in \mathbb{C}^{l \times m}$, and the matrix-valued function $\Phi(\cdot) \in L_{p^{\prime}}\left([a, b] ; \mathbb{C}^{l \times m}\right), 1 / p+1 / p^{\prime}=1$.

For $p=\infty$ this formula also defines an operator $B:\left(W_{\infty}^{n+r}\right)^{m} \rightarrow \mathbb{C}^{l}$. However, there exist other operators from this class generated by the integrals over finitely additive measures.

## Index of problem

With problem (1), (2), we associate the linear operator

$$
\begin{equation*}
(L, B):\left(W_{p}^{n+r}\right)^{m} \rightarrow\left(W_{p}^{n}\right)^{m} \times \mathbb{C}^{l} . \tag{5}
\end{equation*}
$$

Theorem 1.
The linear operator (5) is a bounded Fredholm operator with index $m r-l$.

## Characteristic matrix

Family of matrix Cauchy problems with the initial conditions

$$
\begin{gathered}
Y_{k}^{(r)}(t)+\sum_{j=1}^{r} A_{r-j}(t) Y_{k}^{(r-j)}(t)=O_{m}, \quad t \in(a, b), \\
Y_{k}^{(j-1)}(a)=\delta_{k, j} I_{m}, \quad j \in\{1, \ldots, r\} .
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\end{gathered}
$$

By $\left[B Y_{k}\right]$, we denote the numerical $m \times l$ matrix, in which $j$-th column is result of the action of $B$ on $j$-th column of $Y_{k}(\cdot)$.

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## Definition 1.

A block numerical matrix

$$
\begin{equation*}
\mathrm{M}(\mathrm{~L}, \mathrm{~B}):=\left(\left[B Y_{0}\right], \ldots,\left[B Y_{r-1}\right]\right) \in \mathbb{C}^{r m \times l} \tag{6}
\end{equation*}
$$

is characteristic matrix to problem (1), (2). It consists of $r$ rectangular block columns $\left[B Y_{k}(\cdot)\right] \in \mathbb{C}^{m \times l}$.

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is characteristic matrix to problem (1), (2). It consists of $r$ rectangular block columns $\left[B Y_{k}(\cdot)\right] \in \mathbb{C}^{m \times l}$.

If $B=0$, then $M(L, B)=O_{r m \times l}$ for all $L$.

## Solvability of problem

Theorem 2.
The dimensions of kernel and cokernel of the operator (5) are equal to the dimensions of kernel and cokernel of matrix (6), respectively:

$$
\begin{aligned}
\operatorname{dim} \operatorname{ker}(L, B) & =\operatorname{dim} \operatorname{ker}(M(L, B)) \\
\operatorname{dim} \operatorname{coker}(L, B) & =\operatorname{dim} \operatorname{coker}(M(L, B)) .
\end{aligned}
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\end{aligned}
$$

## Corollary 1.

The operator (5) is invertible if and only if $l=m r$ and the square matrix $M(L, B)$ is nondegenerate.

## Example 2 (one-point problem)

Consider a linear one-point boundary-value problem

$$
\begin{gather*}
L y(t):=y^{\prime}(t)+A y(t)=f(t), \quad t \in(a, b), \\
B y=\sum_{k=0}^{n-1} \alpha_{k} y^{(k)}(a)=c . \tag{7}
\end{gather*}
$$

Here, $A$ is a constant $m \times m$-matrix, $f(\cdot) \in\left(W_{p}^{n-1}\right)^{m}, \alpha_{k} \in \mathbb{C}^{l \times m}, c \in \mathbb{C}^{l}$,

$$
B:\left(W_{p}^{n}\right)^{m} \rightarrow \mathbb{C}^{l}, \quad(L, B):\left(W_{p}^{n}\right)^{m} \rightarrow\left(W_{p}^{n-1}\right)^{m} \times \mathbb{C}^{l},
$$

$y(\cdot) \in\left(W_{p}^{n}\right)^{m}$.
We denote by $Y(\cdot) \in\left(W_{p}^{n}\right)^{m \times m}$ the unique solution of the Cauchy matrix problem

$$
Y^{\prime}(t)+A Y(t)=O_{m}, \quad t \in(a, b), \quad Y(a)=I_{m} .
$$

## Example 2 (one-point problem)

Then the matrix-valued function $Y(\cdot)$ and its $k$-th derivative will have the following form:

$$
\begin{gathered}
Y(t)=\exp (-A(t-a)), \quad Y(a)=I_{m} \\
Y^{(k)}(t)=(-A)^{k} \exp (-A(t-a)), \quad Y^{(k)}(a)=(-A)^{k}, \quad k \in \mathbb{N} .
\end{gathered}
$$

Substituting these values into the equality (7), we have

$$
M(L, B)=\sum_{k=0}^{n-1} \alpha_{k}(-A)^{k}
$$

It follows from Theorem 1 that $\operatorname{ind}(L, B)=\operatorname{ind}(M(L, B))=m-l$.
Therefore, by Theorem 2, we obtain

$$
\operatorname{dim} \operatorname{ker}(L, B)=\operatorname{dim} \operatorname{ker}\left(\sum_{k=0}^{n-1} \alpha_{k}(-A)^{k}\right)=m-\operatorname{rank}\left(\sum_{k=0}^{n-1} \alpha_{k}(-A)^{k}\right),
$$

$\operatorname{dim} \operatorname{coker}(L, B)=-m+l+\operatorname{dim} \operatorname{ker}\left(\sum_{k=0}^{n-1} \alpha_{k}(-A)^{k}\right)=l-\operatorname{rank}\left(\sum_{k=0}^{n-1} \alpha_{k}(-A)^{k}\right)$

## Example 3 (two-point problem)

Consider the two-point boundary-value problem with the coefficient $A(t) \equiv O_{m}$ and the boundary conditions at the points $\left\{t_{0}, t_{1}\right\} \subset[a, b]$ containing derivatives of integer and / or fractional orders. They are given by equality

$$
\begin{aligned}
& L y(t):=y^{\prime}(t)+A y(t)=f(t), \quad t \in(a, b) \\
& B y=\sum_{j} \alpha_{0 j} y^{\left(\beta_{0 j}\right)}\left(t_{0}\right)+\sum_{j} \alpha_{1 j} y^{\left(\beta_{1 j}\right)}\left(t_{1}\right)
\end{aligned}
$$

Here, both sums are finite, numerical matrices $\alpha_{k j} \in \mathbb{C}^{l \times m}$. In this case, the matrix-valued function $Y(\cdot)=I_{m}$. Therefore, the characteristic matrix has the form

$$
M(L, B)=\sum_{j} \alpha_{0 j} I_{m}^{\left(\beta_{0 j}\right)}+\sum_{j} \alpha_{1 j} I_{m}^{\left(\beta_{1 j}\right)}=\alpha_{0,0}+\alpha_{1,0}
$$

because the derivatives $I_{m}^{\left(\beta_{k j}\right)}=0$.

## Example 3 (two-point problem)

Therefore, by Theorem 2, we have
$\operatorname{dim} \operatorname{ker}(L, B)=\operatorname{dim} \operatorname{ker}\left(\alpha_{0,0}+\alpha_{1,0}\right)=m-\operatorname{rank}\left(\alpha_{0,0}+\alpha_{1,0}\right)$, $\operatorname{dim} \operatorname{coker}(L, B)=\operatorname{dim} \operatorname{ker}\left(\alpha_{0,0}+\alpha_{1,0}\right)-m+l=l-\operatorname{rank}\left(\alpha_{0,0}+\alpha_{1,0}\right)$.

## Example 4 (multipoint problem)

Consider problem (1), (2), where $r=1$, putting $A(t) \equiv 0$ with the next boundary conditions:

$$
B y=\sum_{k=0}^{n-1} \alpha_{k} y^{(k)}(a)+\int_{a}^{b} \Phi(t) y^{(n)}(t) \mathrm{d} t, \quad y(\cdot) \in\left(W_{p}^{n}\right)^{m}
$$

Then we have

$$
\begin{gathered}
B Y=\sum_{s=0}^{n-1} \alpha_{s} Y^{(s)}(a)+\int_{a}^{b} \Phi(t) Y^{(n)}(t) \mathrm{d} t, \quad Y(\cdot)=I_{m} \\
M(L, B)=\alpha_{0}
\end{gathered}
$$

The numerical matrix $\alpha_{0}$ does not depend on $p, \alpha_{1}, \ldots, \alpha_{n-1}$, and $\Phi(\cdot)$. Thus, the statement of Theorem 2 holds:

$$
\begin{aligned}
\operatorname{dim} \operatorname{ker}(M(L, B)) & =\operatorname{dim} \operatorname{ker}\left(\alpha_{0}\right) \\
\operatorname{dim} \operatorname{coker}(M(L, B)) & =\operatorname{dim} \operatorname{coker}\left(\alpha_{0}\right)
\end{aligned}
$$

## Application

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Boundary-value problems depending on $k \in \mathbb{N}$

$$
\begin{gather*}
L(k) y(t, k):=y^{(r)}(t, k)+\sum_{j=1}^{r} A_{r-j}(t, k) y^{(r-j)}(t, k)=f(t, k), \quad t \in(a, b),  \tag{8}\\
B(k) y(\cdot, k)=c(k), \quad k \in \mathbb{N} . \tag{9}
\end{gather*}
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B(k) y(\cdot, k)=c(k), \quad k \in \mathbb{N} . \tag{9}
\end{gather*}
$$

The sequence of linear continuous operators

$$
(L(k), B(k)):\left(W_{p}^{n+r}\right)^{m} \rightarrow\left(W_{p}^{n}\right)^{m} \times \mathbb{C}^{l},
$$

and characteristic matrices

$$
M(L(k), B(k)):=\left(\left[B(k) Y_{0}(\cdot, k)\right], \ldots,\left[B(k) Y_{r-1}(\cdot, k)\right]\right) \subset \mathbb{C}^{m r \times l}
$$

## Convergence of the characteristic matrices

Let's formulate a sufficient condition for convergence of the characteristic matrices.

## Theorem 3.

If the sequence of operators $(L(k), B(k))$ converges strongly to the operator $(L, B)$ then the sequence of characteristic matrices $M(L(k), B(k))$ converges to the matrix $M(L, B)$ for $k \rightarrow \infty$.

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From Theorem 3 follows sufficient conditions of semicontinuity from above the dimensions of the kernel and cokernel of the operator $(L, B)$.

## Corollary 2.

Under assumptions in Theorem 3, the following inequalities hold starting with sufficiently large $k$ :

$$
\begin{gathered}
\operatorname{dim} \operatorname{ker}(L(k), B(k)) \leq \operatorname{dim} \operatorname{ker}(L, B), \\
\operatorname{dim} \operatorname{coker}(L(k), B(k)) \leq \operatorname{dim} \operatorname{coker}(L, B) .
\end{gathered}
$$

## Remark

The Corollary 2 implies the consequences of the stability of the invertibility of the sequence of operators $(L(k), B(k))$, the existence and uniqueness of the solution to problem (8), (9). In particular, for sufficiently large $k$, we have:

1) if $l=m r$ and operator $(L, B)$ is invertible, then the operators $(L(k), B(k))$ are also invertible;
2) if problem (1), (2) has a solution, then problems (8), (9) also have a solution;

3 ) if problem (1), (2) has a unique solution, then problems (8), (9) also have a unique solution.

## Application

For each $k \rightarrow \infty$, we write the operator $B(k)$ in the form (4), where $\alpha_{s}=\alpha_{s}(k)$, $\Phi(t)=\Phi(t, k)$.
In the case of $1 \leq p<\infty$, based on a unique analytic representation of the operator $B$ in (4), we formulate necessary and sufficient conditions that guarantees a strong convergence of the sequence of operators $(L(k), B(k))$ to the operator $(L, B)$.

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## Theorem 4.

Condition $(L(k), B(k)) \xrightarrow{s}(L, B)$ is equivalent to conditions:

1. $\|L(k)-L\| \rightarrow 0$;
2. $L(k) y \rightarrow L y$ for each $y \in\left(W_{p}^{n+r}\right)^{m}$;
3. $\alpha_{s}(k) \rightarrow \alpha_{s}$ in $\mathbb{C}^{l \times m}$ for each $s \in\{0, \ldots, n-1\}$;
4. $\|\Phi(\cdot, k)\|_{q}=O(1)$;
5. $\int_{a}^{t} \Phi(\tau, k) d \tau \rightarrow \int_{a}^{t} \Phi(\tau) d \tau$ in $\mathbb{C}^{l \times m}$ for each $t \in(a, b]$.

## Application

In the case of $1 \leq p<\infty$, we formulate necessary and sufficient conditions that guarantees the uniform convergence of the sequence of operators $(L(k), B(k))$ to the operator $(L, B)$.

## Theorem 5.

Condition $\|(L(k), B(k))-(L, B)\| \rightarrow 0$ is equivalent to conditions:

$$
\begin{aligned}
& \text { 1. }\|L(k)-L\| \rightarrow 0 ; \\
& \text { 6. }\|\Phi(\cdot, k)-\Phi(\cdot)\|_{q} \rightarrow 0 \text {. }
\end{aligned}
$$

The condition 6 is stronger than conditions 4 and 5 .

## Example 5

$$
\begin{equation*}
L(k) y(t, k):=y^{\prime}(t, k)+A(t, k) y(t, k)=f(t, k), \quad B(k) y(\cdot, k)=c(k) . \tag{10}
\end{equation*}
$$

Denote by $Y(\cdot, k) \in\left(W_{p}^{n}\right)^{m \times m}$, respectively, the solution of the sequence of matrix differential equations

$$
\begin{equation*}
Y^{\prime}(t, k)+A(t, k) Y(t, k)=0, \quad t \in(a, b), \quad k \in \mathbb{N}, \quad Y(a, k)=I_{m} . \tag{11}
\end{equation*}
$$

Denote by $M(L(k), B(k)):=[B(k) Y(\cdot, k)] \in \mathbb{C}^{m \times l}$.

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$$

Denote by $M(L(k), B(k)):=[B(k) Y(\cdot, k)] \in \mathbb{C}^{m \times l}$. From (4), we have

$$
\begin{equation*}
B(k) Y=\sum_{s=0}^{n-1} \alpha_{s}(k) Y^{(s)}(a)+\int_{a}^{b} \Phi(t, k) Y^{(n)}(t) \mathrm{d} t \tag{12}
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\end{equation*}
$$

Suppose that for the problem (10) the conditions of the Theorem 4 are satisfied:
a) $\alpha_{s}(k) \rightarrow \alpha_{s}$ in $\mathbb{C}^{l \times m}$ for each $s \in\{0, \ldots, n-1\}$;
b) $\|\Phi(\cdot, k)\|_{q}=O(1)$;
c) $\int_{a}^{t} \Phi(\tau, k) d \tau \rightarrow \int_{a}^{t} \Phi(\tau) d \tau$ in $\mathbb{C}^{l \times m}$ for each $t \in(a, b]$.

## Example 5

Then we have a strong convergence of the sequence of operators $(L(k), B(k))$ to the operator $(L, B)$.
Then by the Theorem 3 we have the convergence of the sequence of characteristic matrices.
In (11), put $A(t, k) \rightarrow 0$, then $Y(t, k) \rightarrow I_{m}$. Substituting this value into equality (12), we have

$$
M(L(k), B(k)) \rightarrow \alpha_{0} .
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## Example 5

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In (11), put $A(t, k) \rightarrow 0$, then $Y(t, k) \rightarrow I_{m}$. Substituting this value into equality (12), we have

$$
M(L(k), B(k)) \rightarrow \alpha_{0} .
$$

Therefore, starting with some number $k$

$$
\begin{gathered}
\operatorname{dim} \operatorname{ker}(M(L(k), B(k))) \leq \operatorname{dim} \operatorname{ker}\left(\alpha_{0}\right), \\
\operatorname{dim} \operatorname{coker}(M(L(k), B(k))) \leq \operatorname{dim} \operatorname{coker}\left(\alpha_{0}\right) .
\end{gathered}
$$

In particular, if the numerical matrix $\alpha_{0}$ is square and nondegenerate, then starting from some number $k_{0}$ all boundary-value problems are well-posedness.

## Approximation

Linear boundary-value problem

$$
\begin{equation*}
(L y)(t):=y^{(r)}(t)+\sum_{j=1}^{r} A_{r-j}(t) y^{(r-j)}(t)=f(t), \quad t \in(a, b), \tag{13}
\end{equation*}
$$

$$
\begin{equation*}
B y=c, \tag{14}
\end{equation*}
$$

where $1 \leq p<\infty$.
A sequence of multipoint boundary-value problems

$$
\begin{gather*}
\left(L_{k} y_{k}\right)(t):=y_{k}^{(r)}(t)+\sum_{j=1}^{r} A_{r-j}(t) y_{k}^{(r-j)}(t)=f(t), \quad t \in(a, b),  \tag{15}\\
B_{k} y_{k}:=\sum_{j=0}^{N} \sum_{l=0}^{n+r-1} \beta_{k}^{(l, j)} y^{(l)}\left(t_{k, j}\right)=c . \tag{16}
\end{gather*}
$$

## Approximation

## Theorem 10.

For the boundary-value problem (13), (14) there is a sequence of multipoint boundary-value problems of the form (15), (16) such that they are well-posedness for sufficiently large $k$ and the asymptotic property is fulfilled

$$
y_{k} \rightarrow y \quad \text { in } \quad\left(W_{p}^{n+r}\right)^{m} \quad \text { for } \quad k \rightarrow \infty .
$$

The sequence can be chosen independently of $f$ and $c$, and constructed explicitly.

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## Thank you!



